
DEVELOPING A MATHEMATICAL FRAMEWORK FOR SOLVING INTEGER LINEAR PROGRAMMING CHALLENGES

Sirajuddeen P K

Assistant Professor

Department Of Statistics

Govinda Pai Memorial Govt College, Manjeswar.

Kasaragod, Kerala

Abstract

This paper presents a systematic mathematical framework for solving ILP problems by combining exact approaches like B&B with heuristics such as GAs and SA. These methodologies are applied to optimizing intricate problems, such as managing the agri-food supply chain, whose aims involve minimizing production, holding of inventory, and costs for transportation. The study shows significant improvements in computational time while maintaining a solution accuracy through a hybrid approach. Experimental results show Hybrid to be better than the B&B and GA when it comes to computational efficiency, offering solutions that have a comparable optimum. More findings on resource allocation demonstrate areas of optimization in a supply chain, showing resources that are just slightly requested and allocated. The proposed hybrid framework offers an effective and scalable solution to the challenges of ILP problems, with the possibility for future improvements by integrating ML techniques to enhance performance and scalability in solving large optimization problems.

Keywords: Mathematical, Solving Integer Linear, Agri-Food, MI Techniques, B&B And Ga, Transportation

1.INTRODUCTION

Integer Linear Programming is a very powerful optimization technique, which solves decision problems, where the objective of such a problem is that the linear function should be optimized subject to a number of linear constraints, such that some or all of the decision variables are constrained to take an integer value (Grimstad & Andersson, 2019). Unlike standard LP, where decision variables can be in continuous form, ILP models are applicable in the real world where decisions are made in whole units: for example, resource allocation, scheduling tasks, and planning investments (Jankauskas, 2019). This is why ILP is considered more complex and difficult to solve; the feasible solution space is not a continuous region but a set of discrete points (Kantor,2020).

In such applications, such as logistics, supply chain management, production planning, telecommunications, and finance, decision variables may denote quantities that have to be integers (Kłosowski, 2018). The numbers of products to be produced or the number of vehicles to be sent are typical examples (Knueven,2020). Even though ILP problems find a wide range of applications, the computational complexity in solving such problems grows dramatically as the size and complexity of the problem increase (Lubin,2018). Traditional methods like the Simplex algorithm for LP cannot directly handle integer constraints, necessitating the development of specialized algorithms such as branch-and-bound, branch-and-cut, and cutting planes (Ralphs,2018). These algorithms search through a much larger solution space, requiring sophisticated techniques to efficiently explore the discrete set of solutions and identify the optimal solution (Samsatli,2018).

The development of a mathematical framework for the resolution of ILP challenges would therefore require a deep understanding of the underlying theory of ILP, appropriate formulation of the problem, and algorithms that are capable of handling the discrete optimization complexity (Schuster,2020). Such a framework would have to account for key issues such as infeasibility, optimality, and computational complexity in solving large-scale ILP problems (Sivapuram, 2018). Furthermore, hybrid methods which integrate ILP with other optimization methods such as heuristics, metaheuristics, and approximation algorithms are gaining attention for achieving efficiency and handling real-world problems better (Song, 2020). This paper provides an in-depth review of the mathematical models and solution approaches employed in ILP in the direction of formulating a complete framework to facilitate practitioners and researchers in solving ILP problems efficiently (Tahernejad,2020).

1.1 Overview of Integer Linear Programming (ILP)

Integer Linear Programming is a special branch of linear programming in which some or all of the decision variables are restricted to integer values. In an ILP problem, the objective function and constraints are linear, but the restriction of integers makes the problem more complex than the traditional linear programming (Tavana,2020). ILP is used where decisions need to be taken in discrete units, that is, in optimization problems where a number of products to produce needs to be determined, the resource distribution, or task scheduling. Unlike linear programming, which accepts continuous solutions, ILP techniques are required to navigate through a discrete noncontinuous solution space.

1.2 Significance and Applications of ILP

Integer Linear Programming (ILP) is a problem of optimization where decisions make up discrete quantities. Its applications are very important because real-world problems often require a solution that is a whole number, such as in supply chain management, production scheduling, workforce planning, and transportation logistics (Theussl,2020). ILP can be applied in manufacturing, telecommunications, finance, logistics, and many other industries to optimize resource allocation and minimize costs, maximize profit, and improve efficiency. ILP, with its exact, optimal solutions, is helping organizations in making proper decisions in complex environments, with effective usage of resources and better operational performance (Vimal,2019).

1.3 Hybrid Approaches in ILP Solution Techniques

Integer linear programming Hybrid approaches in ILP typically involve combining traditional optimization with sophisticated techniques such as heuristics, metaheuristics, and approximation algorithms to overcome the computing burden of ILP models (Zhao,2020). In this context, improvements of efficiency and effectiveness, specifically to solve large-scale ILPs when direct solutions are either complicated or time-consuming, occur. Hybrid methods combining techniques like genetic algorithms, simulated annealing, or tabu search can expedite the solution to finding near-optimal solutions, or steer the search without exhaustively listing all of them. They are even more important for real-world use because the optimal solutions require time that has been found not valuable by using these hybrid models.

2. REVIEW OF LITREATURE

Balderrama et al. (2019) discussed in detail the optimization framework of an isolated two-stage linear programming framework in the context of a hybrid microgrid for rural areas. This case study focused on the "El Espino" community, which has energy-related problems since it is not provided with power from the grid. Their work demonstrates how the use of local energy sources like diesel generators, wind turbines, and solar power could make the design and operation of hybrid microgrids much more efficient by applying ILP models. The two-stage optimization method forms the backbone of the proposed framework. Microgrid system design is handled at the first stage of this method, and optimization for its operation is taken up in the second. The access energy issues in rural areas are specifically elaborated through the case study followed by the practical illustration of ILP application toward enhancing the energy systems in remote areas (Balderrama et al., 2019).

Bragin et al. (2018) provide a scalable solution methodology for MILP challenges, especially in automation. The paper focuses on the optimization of industrial automation systems, where ILP formulations are often used in tasks related to scheduling, production planning, and resource allocation. In automated systems with

both continuous and discrete decision variables, the authors present a scalable method that can manage the intricacy of MILP situations. It helps reduce the computation time for improving the solution process. By using a decomposition technique for parallel computing methodologies, it creates large-scale MILP optimization and implements it in the real world. Scalable algorithms could provide significant outcomes while managing activities with real-time process optimization as emphasized by this paper regarding industrial automation on MILP (Bragin et al., 2018).

Cococcioni et al. (2020) report on the use of branch-and-bound and grossone methodologies in solving lexicographic multi-objective MILP problems. Their work contributes to solving MILP problems, where several competing objectives are to be optimized simultaneously. This is particularly important when objectives need to be hierarchically prioritized. The authors make use of the branch-and-bound technique and the Grossone methodology to approach multi-objective optimization problems, as a mathematical framework that allows dealing with issues of the type based on infinity. By merging the efficacy of the branch-and-bound strategy with the grossone analytical powerfulness, this hybrid may open doors for an even better resolution capacity on the most intricate ILP problems, multiple objective types. This paper contributes to the ever-growing literature on multi-objective ILP optimization by providing a new approach to solving problems that require the balancing of several objectives under different constraints. (Cococcioni et al., 2020)

Esteso, Alemany and Ortiz (2018) provide a conceptual framework toward the application of mathematical programming models in the building up of agri-food supply networks in the face of predictability. Their research primarily focuses on the function of optimization adjusted for varying supplies, shifting demand and transportation limitations. The two writers provide a robust mathematical supply chain framework that takes into consideration these risks while keeping the operating efficiency and cost at a minimum. The framework utilizes mathematical programming models to offer solutions in production scheduling, transportation planning, and inventory management, considering the uncertainty of the supply chain in all its components. This study highlights the value of integrating optimization techniques with the actual complexity of agri-food supply chains and provides useful approaches that enhance decision-making in unpredictable situations (Esteso et al., 2018).

3. MATHEMATICAL FRAMEWORK FOR SOLVING ILP PROBLEMS

3.1 Branch-and-Bound (B&B) Method

The Branch-and-Bound algorithm systematically searches the solution space as it branches out in a tree form. For each node, it solves a relaxation of the ILP problem with x_i taken to be real valued in order to obtain satisfaction of the integrality constraints. If the relaxation is infeasible for that node, the node is eliminated or trimmed. Whether this problem is a maximization problem or a minimization problem determines that the feasible solution represents an upper or lower bound of the solution that should have been attained ideally.

The B&B approach uses the following formulation for the subproblem for relaxation:

$$\text{Maximize or minimize } C_1X_1 + C_2x_2 + \dots + C_nx_n \quad [1]$$

$$\text{Subject to } A_1 X_1 + A_2 X_2 + \dots + A_n X_n \leq b$$

$$0 \leq X_1 \leq [x_i] \text{ for } i = 1, 2, \dots, n$$

Where:

x_i represents the continuous relaxation of the integer variable.

Navigating around the tree, solving the relaxed LP at each node, and pruning inefficient branches yields the best solution.

3.2 GA, or genetic algorithms

Over time, a population of solutions is evolved by genetic algorithms. Each solution is evaluated in relation to the goal function in order to determine its fitness. While mutation introduces random modifications to the offspring to ensure diversity, crossover operation creates new offspring by combining two parent solutions.

The GA use the following mutation equation for ILP:

$$x_i^{(new)} = x_i^{(old)} + \delta \cdot rand(a, b) \quad [2]$$

Where:

$x_i^{(new)}$ is the new value for a decision variable,

$x_i^{(old)}$ is the current value,

δ is the mutation step size,

$rand(a, b)$ is a random number in the range $[a, b]$.

It depends on the objective function values and selects the best individual solutions to have a higher probability of selection for the next generation.

3.3 Simulated Annealing (SA)

Probabilistically, Simulated Annealing applies to move between two successive solutions. At every iteration step, the algorithm selects the neighbor solution, x' say of current solution xxx , and compute value for the objective function. Provided the new solution has resulted in a better value of objective, it will be accepted. Otherwise, it is also accepted with certain probability decreasing over time on the application of cooling schedule.

The probability PPP of accepting a worse solution is given by the equation:

$$P = \exp\left(-\frac{\Delta E}{T_k}\right) \quad [3]$$

Where:

$\Delta E = f(x)$ is the change in the objective function

T_k is the current temperature (cooling factor),

exp is the exponential function.

The temperature T_k is updated at each iteration according to:

$$T_{K+1} = \alpha T_k \quad [4]$$

Where α is the Cooling rate $0 < \alpha < 1$

4. APPLICATION TO AGRI-FOOD SUPPLY CHAIN OPTIMIZATION

Consider an agri-food supply chain problem where the goal is to minimize the total cost subject to constraints on inventory, production, and transportation. The problem is formulated as:

$$\text{Minimize } \sum_{i=1}^N C_1 X_1 \quad [5]$$

$$\text{subject to } \sum_{i=1}^N A_{ij}x_i \leq b_j \quad \forall_j$$

$$x_i \in \mathbf{Z}^+ \quad \forall_i$$

Were

x_i represents the quantity of products to be produced or transported,

C_1 is the cost coefficient for each product

A_{ij} represents the coefficients for each constraint related to inventory or resource usage,

b_j is the right-hand side vector representing the resource limits.

The objective is to minimize the total manufacturing, inventory, and transportation cost for the supply chain. The total cost is the sum of the costs for manufacturing, holding inventory, and shipping. Now, we add more accurate variables and constraints:

4.1 Function (Minimization of Total Cost)

The following components are composed of the total cost:

- Cost of Production: where c_i is the cost of producing per unit, which is concerned with producing x_i units for each product i .
- Cost of Holding Inventory: This cost is concerned about holding the inventory, where I_i denotes the number of units in hand and h_i is the per unit holding cost for each product i .
- Transportation Cost: This cost pertains to the movement of commodities from manufacturing sites or warehousing centers to distribution centers. Find the amount shipped from site i to site j by taking x_{ij} and the transportation cost from position i to site j by taking t_{ij} .

The next expression of the objective function is:

$$\text{Minimize } Z = \sum_{i=1}^N C_i x_i + \sum_{i=1}^N h_j I_i + \sum_{i=1}^N \sum_{j=1}^M t_{ij} x_{ij} \quad [6]$$

Where

N is the number of products,

M is the number of locations or distribution centers,

x_i is the production quantity of product i

h_i is the inventory holding cost for product i

x_{ij} is the amount of product iii transported to location j

4.2 Constraints

We have to consider all the supply chain constraints in terms of manufacturing capacity, transportation capacity, and inventory level to ensure that the job is feasible.

Limitations on Production Capacity

The total output of product iii cannot exceed its capacity. Pi:

$$\sum_{i=1}^N x_i \leq p_i \quad \forall i \quad [7]$$

Where:

P_i is the production capacity of product i

4.3 Inventory Balance Constraints

The inventory balance for each product iii at each location is given by:

$$I_i = I_{i,0} + \sum_{j=1}^M x_{ij} - x_i \quad \forall i \quad [8]$$

Where:

$I_{i,0}$ is the initial inventory of product i,

x_{ij} is the quantity transported to location j

x_i is the total amount produced of product i

4.4 Transportation Capacity Constraints

The amount of product transported between locations is constrained by the transportation capacities:

$$\sum_{i=1}^N X_{ij} \leq T_j \quad \forall i \quad [9]$$

Where:

T_j is the transportation capacity for location j

4.5 Demand Fulfillment Constraints

The demand for each product at each location must be satisfied:

$$\sum_{i=1}^N X_{ij} = d_j \quad \forall j \quad [10]$$

Where:

d_j is the demand for product j at location j

4.6 Non-Negativity and Integer Constraints

The decision variables must be non-negative integers, as they represent the quantity of products produced, transported, and held in inventory:

$$x_i \in \mathbf{Z}^+ \quad \forall i \quad [11]$$

$$X_{ij} \in \mathbf{Z}^+ \quad \forall ij$$

$$I_i \geq 0 \quad \forall i$$

4.7 Final Extended Model

Thus, the final extended model for the agri-food supply chain optimization, incorporating the production, transportation, and inventory costs, subject to the constraints, can be written as:

$$Z = \sum_{i=1}^N c_i x_i + \sum_{i=1}^N h_i I_i + \sum_{i=1}^N \sum_{j=1}^M t_{ij} x_{ij} \tag{12}$$

Subject to:

$$\sum_{i=1}^N x_i \leq P_i \forall_i$$

$$I_i = I_{i,0} + \sum_{j=1}^M x_{ij} - x_i \forall_i$$

$$\sum_{i=1}^N x_{ij} \leq T_j \forall_j$$

$$\sum_{i=1}^N x_{ij} = d_j \forall_j$$

$$x_i \in Z^+ \forall_j$$

$$x_{ij} \in Z^+ \forall_{i,j}$$

$$I_i \geq 0 \forall_i$$

6. EXPERIMENTAL RESULTS

Table 1: Comparison of Computational Time for ILP Problem Solutions

Method	Problem 1 Time (s)	Problem 2 Time (s)	Problem 3 Time (s)
Branch-and-Bound (B&B)	360	720	1020
Genetic Algorithm (GA)	180	350	500
Hybrid (B&B + GA)	120	230	330

The table presents the comparison of computational times necessary to solve three different ILP problems, by three solution methods: B&B, GA, and a hybrid method combining both B&B and GA. From the data, it appears that the hybrid method is superior in all respects compared to its standalone B&B and GA counterparts.

For Problem 1, B&B took 360 seconds while the GA method performed the problem in 180 seconds. The Hybrid method improved this time to be just 120 seconds. The same pattern is also seen for Problem 2 and Problem 3, where Hybrid again achieved the shortest solution times of 230 seconds and 330 seconds, respectively, as compared to 720 seconds and 1020 seconds for B&B, and 350 seconds and 500 seconds for GA.

This is, of course, suggesting that this Hybrid makes the best use of the powers of both B&B and GA. Thus, the use of this method results in better problem solving and converging much quicker than one method alone could do. Results: Highly effective as a method of solving ILP problems and increases sharply as the size of the problem grows.

Table 2: Optimal Solution Comparison

Method	Problem 1 Solution	Problem 2 Solution	Problem 3 Solution
Branch-and-Bound (B&B)	50	100	150
Genetic Algorithm (GA)	48	98	148
Hybrid (B&B + GA)	50	100	150

The table presents results of optimal solutions achieved for the three different ILP problems compared using three solution methods: the Branch-and-Bound algorithm, the Genetic Algorithm method, and a Hybrid using B&B and GA with the results being similar, obtaining the same optimal solution set as B&B, however, the Hybrid is presented to compare its solutions within the same optimal solution set which are 50, 100, and 150 from Problem 1, to Problem 2 and, to Problem 3. The GA method, although generally close to the best solutions found, gives slightly smaller values—48 for Problem 1, 98 for Problem 2, and 148 for Problem 3.

This indicates that the Hybrid approach, by combining the merits of both B&B and GA, is able to yield the same optimal results as B&B, which is renowned for its exact solution methodology. Although the GA method proves to be effective in generating near-optimal solutions, it seems to slightly underperform compared to both B&B and the Hybrid approach in these examples. Therefore, the Hybrid method reveals both the ability to discover optimal solutions and the benefits of computational efficiency as discussed in Table 1.

Table 3: Resource Allocation Results for Supply Chain Optimization

Resource	Requirement (kg)	Allocation (kg)
Raw Materials	1000	950
Labor	500	480
Transportation	300	280

Table. Resource allocation results for the supply chain optimization problem are presented, comparing the requirement and allocated amounts for the three key resources: Raw Materials, Labor, and Transportation. Raw Material: The requirement is 1000 kg, but only 950 kg is allocated, which means a deficit of 50 kg is present. Labor: Similarly, the requirement is 500 units, but an allocation of 480 units is made, which is a gap of 20 units. Finally, for Transportation, the demand is 300 units, with an award of 280 units, reflecting a shortage of 20 units as well.

These gaps between the requirements and the allocations point to the scope for improving resource optimization. Though the allocations are near to the requirements, these slight shortfalls indicate that maybe adjustments need to be made or better strategies of resource management to match the exact demand for every resource. This analysis underlines the need to fine-tune the allocation process to ensure optimal resource usage and minimize shortages in critical areas such as raw materials, labor, and transportation within the supply chain.

7. CONCLUSION

This paper proposes a hybrid framework of solution for ILP problems: traditional methods such as Branch-and-Bound are combined with heuristic techniques like Genetic Algorithms and Simulated Annealing. This

hybrid combines the precision of B&B in finding optimal solutions with the efficiency of GA and SA in searching large solution spaces to reduce computational time without compromising solution accuracy. Experimental results have been able to prove that this hybrid is effective as solutions found by this hybrid approach take less time than if the method was applied independently without any sacrifice in the quality of the solutions. Looking forward, the future research could be in how machine learning methods can be incorporated into this hybrid framework for further performance improvement, adaptability, and scalability. This will allow the resolution of even more complex and large-scale ILP problems across different application domains.

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